

Airworthiness challenges for sense, detect and avoid systems

Oct 2022



Definitions

2



Definitions

Detect and avoid: The capability to see, sense or detect conflicting traffic or other hazards and take the appropriate action. (ICAO DOC10019)

- + **Cooperative traffic:** expected to actively cooperate to resolve a conflict with full agreement on each others intent and resolution protocol.
- Non cooperative traffic: either total lack or uncertainty in the intent information and not actively cooperative to resolve a conflict.

(Cooperative and Non-Cooperative UAS Traffic Volumes by Vishwanath Bulusu, Raja Sengupta, Valentin Polishchuk and Leonid Sedov)



Essentials

4



DAA Requirement

→ SERA.3201 General (today)

Nothing in this Regulation shall relieve the pilot-incommand of an aircraft from the responsibility of taking such action, including collision avoidance manoeuvres based on resolution advisories provided by airborne collision avoidance system (ACAS) equipment, as will best avert collision.



Detect and Avoid (DAA)

- Obstacles: towers, chimney
 - What with unmapped obstacles?

- → Other Aircraft
 - + UAS?

→ Birds...



DAA technology

Active DAA

Passive DAA





Database









Vision





Centrally managed

Using GNSS (GPS,...)

List of known obstacles

Audible

Visual spectrum Infrared



Feedback Loop

FEEDBACK LOOP

Steps

	See/Detect	Decide	Command	Execute	
Pilot onboard aircraft maintaining separation and collision avoidance by see ar avoid	Pilot "sees" conflict	Pilot "decides" what to do	Pilot	lot .,, Aircraft	
Air Traffic Controller maintaining separation by radar, pilot onboard aircraft maintaining collision avoidance by see and avoid	Radar "Detects" Conflict	Controller "Decides" what to do	"command" aircraft manoeuvres	"executes" manoeuvres	
DAA maintaining separation and collision avoidance	Sensors "Detect" Conflict	DAA/Pilot "Decides" What to do	DAA/pilot "commands" UA manoeuvres	UA "executes" manoeuvres	

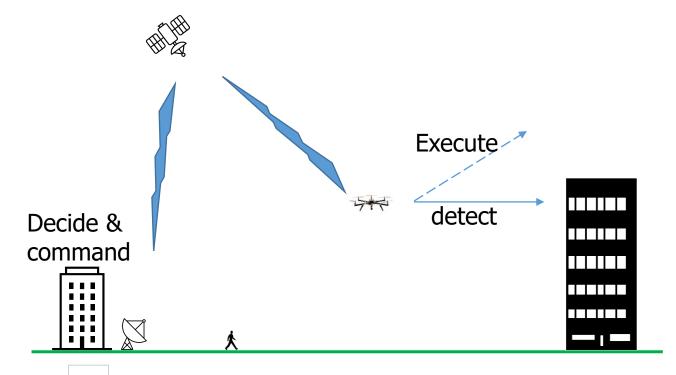




DAA elements

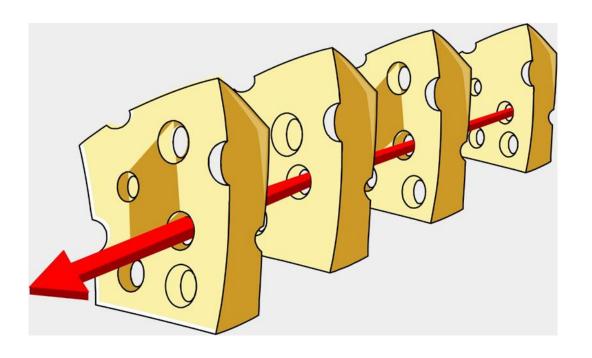
→ On board capacity

- → External capacity
 - + External services?





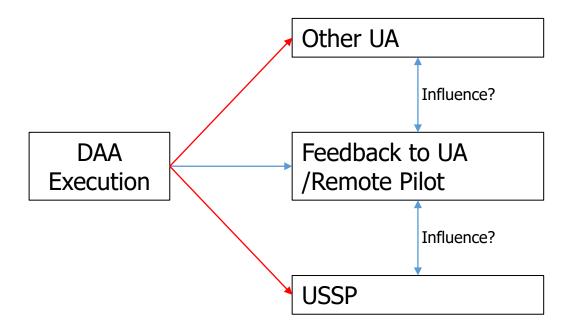
- → Redundancy?
- + Variation?
- + Latency? (external decision)
- + Security?





DAA third party impact







DAA



- + SORA as basis
 - + Tactical Mitigation Performance Requirements
 - + Currently quantitaive requirements
- Depending airspace requirements



+ Detect

ARC-b	ARC-c	ARC-d
50% aircraft in detection volume	90% aircraft in detection volume	A system
 Use of (web-based) real time aircraft tracking services Use Low Cost ADS-B In/UAT/FLARM/Pilot Aware aircraft trackers Use of UTM/U-space Dynamic geofencing Monitoring aeronautical radio communications 	 Ground based DAA /RADAR FLARM Pilot Aware ADS-B In/ UAT In Receiver ATC Separation Services UTM/U-space Surveillance Service UTM/U-space Early Conflict Detection and Resolution Service 	meeting RTCA SC-228 or EUROCAE WG- 105 MOPS/MASPS (or similar) and installed in accordance with applicable requirements. ED-271 (Class A-C IFR)



→ Decide

ARC-b	ARC-c	ARC-d
Deconfliction Scheme	See ARC-b and	A system
tools or methods will be used for detection and what the criteria are that will be applied for the decision to avoid incoming traffic	 Human-Machine assessment Tool and method effectiveness assessment 5 second decisionmaking Failure rate or availablility of method or tool 	meeting RTCA SC-228 or EUROCAE WG- 105 MOPS/MASPS (or similar) and installed in accordance with applicable requirements. ED-271 (Class A-C IFR)



+ Command

ARC-b	ARC-c	ARC-d
Latency	Latency	A system
≤5sec	≤3 sec	meeting RTCA SC-228 or EUROCAE WG- 105 MOPS/MASPS (or similar) and installed in accordance with applicable requirements. ED-271 (Class A-C IFR)



+ Execute

ARC-b	ARC-c	ARC-d
Seek coverage from obstacles	Avoidance manoeuvres Suggested minimum performance criteria:10 • Airspeed: ≥ 50 knots	A system meeting RTCA SC-228 or EUROCAE WG- 105
	 Rate of climb/descend: ≥ 500 ft/min Turn rate: ≥ 3 degrees per second 	MOPS/MASPS (or similar) and installed in accordance with applicable requirements. ED-271 (Class A-C IFR)



→ Feedback loop

ARC-b	ARC-c	ARC-d
Performance info feedback to improve decision making	See ARC-b and	A system meeting RTCA
Set distance and information update rate Eg. For an assumed 3 NM threshold, a 5 second update rate and a latency of 10 seconds is considered adequate	assessment of closure rate of information expectation ≤ 3sec update rate	SC-228 or EUROCAE WG- 105 MOPS/MASPS (or similar) and installed in accordance with applicable requirements. ED-271 (Class A-C IFR)



DAA OSO impact



DAA Airworthiness Requirements (Δ OSO)

Passive DAA

	ACTIVE DAA	rassive DAA	L			
	((()))		[\(\sigma\)\)		e e	
	Radar	Database	Audible	Vision	Decentral System	Centrally Managed
Weather	#22-24	N/A	#22-24	#22-24	N/A	N/A
SpaceWeather	#22-24	#11-#13	#22-24	#22-24	#11-#13	#11-#13
C3 Link	If onboard N/A	#06 #13	If onboard N/A	If onboard N/A	If onboard N/A	If onboard N/A

All DAA systems are to be mentioned in all other OSO not mentioned above except #01, #02, #03, #17

Active DAA



DAA efforts



DAA efforts

+ EUROCAE WG-105 SG-1

Ref.	Name	Status	Publication target date
ED-xxx	MOPS for Detect and Avoid (Traffic) under IFR	Draft	28/06/2024
ED-xxx	Minimum Operational Performance Standard for Detect and Avoid in Very Low Level Operations	Draft	30/06/2024
ER-xxx	European Industry Position Report on RTCA SC-147 ACAS sXu	Draft	31/12/2022
ED-271	Minimum Aviation System Performance Standard for Detect and Avoid (Traffic) in Class A-C airspaces	Published	11/05/2022
ED-271A	MASPS for Detect and Avoid (Traffic) under IFR	Draft	30/06/2023
ED-271 Corr 1	MASPS for DAA (Traffic) for Remotely Piloted Aircraft Systems in Airspace Classes A-C under IFR	Published	01/06/2022



ERICA-project

- + SESAR JU
- Development and valdiation of DAA
- + Two timeframes:
 - + 1. initial RPAS demand i non-complex structures
 - → 2. full integration in civil/military airspace in cooperative environment



Summary

- + DAA depends on
 - + Airspace
 - Aircraft to be encountered

- Airworthiness now to include (compared to manend aviation)
 - External/automatic decisionmaking
 - + External systems

BCDC



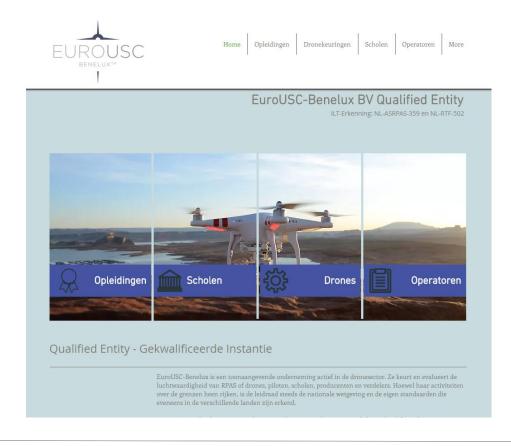
• WG2: Airworthiness

• WG-leader: Thierry Paris

• Contact: thierry.paris@outlook.com



Contact details



www.eurousc.aero

www.eurousc.nl

www.eurousc.be

Tel: +31 85 208 29 23

+32 78 48 05 01

Michael.maes@eurousc.aero